Lecture 4 – Mechanical work and energy Purdue ME 200, Thermodynamics I

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Outline

Differentials

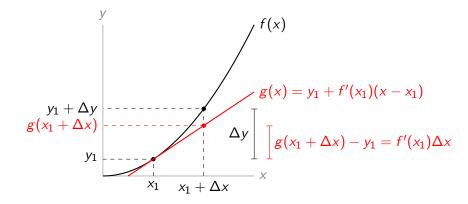
Mechanical work

Conservation of mechanical energy

What are differentials?

- a differential dx is just a tiny (infinitesimal) change in x
- dx can be viewed as the limit of a finite Δx as $\Delta x
 ightarrow 0$
- differentials often show up under integral signs (to calculate total change, add up a bunch of tiny changes)

Differentials in one dimension



- suppose y = f(x) and g is the linear approximation to f at x_1
- when x changes by Δx , y changes by a true amount Δy
- for small Δx , the true $\Delta y \approx f'(x_1)\Delta x$

Differentials in one dimension (continued)

- as $\Delta x \to 0$, the approximation $\Delta y \approx f'(x_1)\Delta x$ becomes exact
- at any arbitrary x, we write

$$dy = f'(x)dx$$
 or $dy = \left(\frac{dy}{dx}\right)dx$

• from the fundamental theorem of calculus,

$$\int_{y_1}^{y_2} dy = \int_{x_1}^{x_2} f'(x) dx = f(x_2) - f(x_1) = y_2 - y_1$$

• more compactly (but less precisely), we can write

$$\int \mathsf{d} y = \Delta y$$

Differentials in two dimensions

- consider a variable z = f(x, y)
- the differential of z is

$$dz = \left(\frac{\partial f}{\partial x}\right)_{y} dx + \left(\frac{\partial f}{\partial y}\right)_{x} dy$$

- in 2D, $\int dz = \Delta z$ only holds for **exact** differentials
- only properties (p, v, T, ...) have exact differentials
- other things (work W, heat Q) have inexact differentials
- we write inexact differentials with δ instead of d
- we never write $\int \delta W = \Delta W$ or $\int \delta Q = \Delta Q$

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General form of mechanical work



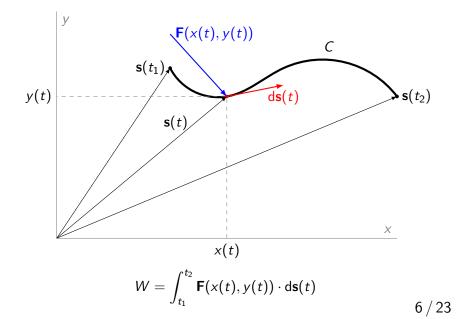
• work done by force **F** on body moved over path C is

$$W = \int_C \mathbf{F} \cdot \mathrm{d}\mathbf{s}$$

- differential displacement ds always points along path
- $\bullet\,$ dot product picks out the component of F along path
- if path starts at point 1 and ends at point 2, we may write

$$W = \int_1^2 \mathbf{F} \cdot \mathrm{d}\mathbf{s}$$

Parameterization in terms of t



Calculating mechanical work

• force can be written as

$$\mathbf{F}(x(t), y(t)) = F_x(x(t), y(t))\mathbf{i} + F_y(x(t), y(t))\mathbf{j}$$

- path C contains all position vectors $\mathbf{s}(t)$ over $t_1 \leq t \leq t_2$
- position vector can be written as $\mathbf{s}(t) = x(t)\mathbf{i} + y(t)\mathbf{j}$
- so differential displacement along path is

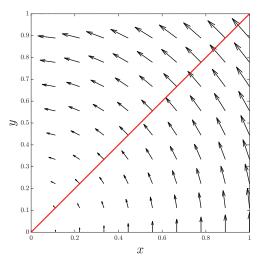
$$d\mathbf{s}(t) = d\mathbf{x}(t)\mathbf{i} + d\mathbf{y}(t)\mathbf{j} = \mathbf{x}'(t)dt\mathbf{i} + \mathbf{y}'(t)dt\mathbf{j}$$

• and work done by force \mathbf{F} over path C is

$$W = \int_{t_1}^{t_2} \left[F_x(x(t), y(t)) x'(t) + F_y(x(t), y(t)) y'(t) \right] dt$$

Example

- suppose force is $\mathbf{F}(x(t), y(t)) = -y(t)\mathbf{i} + x(t)\mathbf{j}$
- and path is $\mathbf{s}(t) = t\mathbf{i} + t\mathbf{j}, \ 0 \le t \le 1$



Solution

- force is perpendicular to path, so $\mathbf{F} \cdot d\mathbf{s} = 0$ and W = 0
- does the math agree?

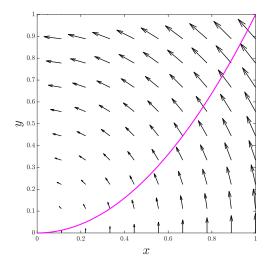
$$\begin{aligned} x(t) &= t, \ y(t) = t \\ x'(t) &= 1, \ y'(t) = 1 \\ F_x(x(t), y(t)) &= -y(t) = -t \\ F_y(x(t), y(t)) &= x(t) = t \end{aligned}$$

• therefore,

$$W = \int_{t_1}^{t_2} \left[F_x(x(t), y(t)) x'(t) + F_y(x(t), y(t)) y'(t) \right] dt$$
$$= \int_0^1 \left[(-t)(1) + (t)(1) \right] dt = 0$$

Modified example

• what if path instead is $\mathbf{s}(t) = t\mathbf{i} + t^2\mathbf{j}, \ 0 \le t \le 1$



Modified solution

- force is no longer perpendicular to path, so $\textbf{F}\cdot d\textbf{s}\neq 0$
- along the modified path,

$$\begin{aligned} x(t) &= t, \ y(t) = t^2 \\ x'(t) &= 1, \ y'(t) = 2t \\ F_x(x(t), y(t)) &= -y(t) = -t^2 \\ F_y(x(t), y(t)) &= x(t) = t \end{aligned}$$

• so the work is

$$W = \int_{t_1}^{t_2} \left[F_x(x(t), y(t)) x'(t) + F_y(x(t), y(t)) y'(t) \right] dt$$

= $\int_0^1 \left[(-t^2)(1) + (t)(2t) \right] dt$
= $\int_0^1 \left(2t^2 - t^2 \right) dt = \frac{1}{3} \neq 0$

Work is path-dependent

- these examples show that work is **path-dependent**
- we can't know the work done without knowing the path taken
- this implies that work is not a property
- as a reminder, we write differential work as δW , not dW
- and we never write $\int \delta W = \Delta W$

Work and power

- power \dot{W} is defined as the time derivative of work
- from the fundamental theorem of calculus, $W = \int_{t_1}^{t_2} \dot{W} dt$
- earlier, we found that

$$W = \int_{t_1}^{t_2} \left[F_x(x(t), y(t)) x'(t) + F_y(x(t), y(t)) y'(t) \right] dt$$

• the integrand is the dot product of F(x(t), y(t)) and velocity,

$$\mathbf{v}(t) = x'(t)\mathbf{i} + y'(t)\mathbf{j}$$

• so
$$W = \int_{t_1}^{t_2} \mathbf{F} \cdot \mathbf{v} dt$$
, and therefore

$$\dot{W} = \mathbf{F} \cdot \mathbf{v}$$

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Differentials

Mechanical work

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Mechanical work and energy in one dimension

- consider a body of mass m at height y and (vertical) speed v
- its kinetic energy (KE) is $\frac{1}{2}mv^2$
- its gravitational potential energy (PE) is mgy (defining PE = 0 at y = 0)
- suppose some other forces, summing to F, act on the body
- if the body moves from y_1 to y_2 , those forces do work

$$W = \int_{y_1}^{y_2} F \mathrm{d} y$$

Conservation of energy in one dimension



- Newton's second law: F mg = ma
- integrate both sides over y from y_1 to y_2 :

$$\int_{y_1}^{y_2} (F - mg) \mathrm{d}y = m \int_{y_1}^{y_2} \mathrm{a} \mathrm{d}y$$

• the left-hand side is

$$\int_{y_1}^{y_2} (F - mg) dy = \int_{y_1}^{y_2} F dy - mg(y_2 - y_1) = W - \Delta \mathsf{PE}$$

15 / 23

Conservation of energy in one dimension (continued)

• the right-hand side is

$$m\int_{y_1}^{y_2} a dy = m\int_{y_1}^{y_2} \frac{dv}{dt} dy = m\int_{y_1}^{y_2} \frac{dv}{dy} \frac{dy}{dt} dy = m\int_{y_1}^{y_2} v \frac{dv}{dy} dy$$

• change variables of integration from y to v:

$$\diamond \ v = v_1 \text{ at } y = y_1 \text{, and } v = v_2 \text{ at } y = y_2$$

- \diamond since v is a function of y, its differential is dv = (dv/dy)dy
- then the integral becomes

$$m \int_{v_1}^{v_2} v dv = m \left[\frac{1}{2} v^2 \right]_{v_1}^{v_2} = \frac{1}{2} m (v_2^2 - v_1^2) = \Delta K E$$

Conservation of energy in one dimension (continued)

• putting the left- and right-hand sides together gives

 $\Delta KE + \Delta PE = W$

- this is conservation of (mechanical) energy in one dimension
- $\bullet\,$ although the derivation was 1D, the result holds in 2D and 3D
- this is a special case of the 1st law of thermodynamics
- we'll progressively generalize the 1st law to include
 - $\diamond~$ other types of work
 - \diamond internal energy
 - ◊ heat transfer
 - ◊ mass transfer

Sign convention

- $\bullet\,$ in this derivation, W was work done by forces on body
- we usually take W to be work done by system on surroundings (historically, thermo focused on work done by heat engines)
- with this sign convention, 1st law becomes

 $\Delta KE + \Delta PE = -W$

Example

1,000 kg of water, initially at rest, flows through a vertical displacement of 60 m in a frictionless pipe. At the bottom, the water flows through a turbine, which it exits at 20 m/s.

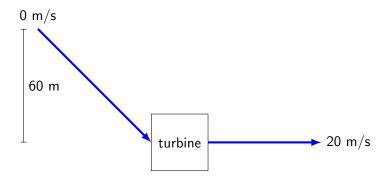
- (a) How much mechanical work does the water do on the turbine?
- (b) If this takes 10 s, what is the average mechanical power?

Given and find

• given

- $\diamond \ m = 1000 \ \rm kg$
- $\diamond~\Delta z = 60~\text{m}$
- $\diamond v_1 = 0 m/s$
- $\diamond v_2 = 20 \text{ m/s}$
- find
 - (a) mechanical work W done by water on turbine
 - (b) average mechanical power W_{av} over $\Delta t = 10$ s

System diagram



Assumptions and basic equations

• assumptions

◊ frictionless pipe (so no energy lost inside)

• basic equations

$$\diamond \ \Delta \mathsf{KE} + \Delta \mathsf{PE} = -W$$

♦ also definitions: $KE = \frac{1}{2}mv^2$, PE = mgz

Solution

• change in kinetic energy is

$$\Delta \mathsf{KE} = \frac{1}{2}m(v_2^2 - v_1^2) = \frac{1}{2}(1000 \, \text{kg})[(20 \, \text{m/s})^2 - (0 \, \text{m/s})^2] = 200 \, \text{kJ}$$

• change in potential energy is

$$\Delta PE = mg\Delta z = (1000 \text{kg})(10 \text{m/s}^2)(0 \text{m} - 60 \text{m}) = -600 \text{kJ}$$

• mechanical work done by water on turbine is

$$W = -(\Delta KE + \Delta PE) = 400 kJ$$

• average mechanical power is

$$\dot{W}_{av} = rac{W}{\Delta t} = rac{400 \text{kJ}}{10 \text{s}} = 40 \text{kW}$$